

17A Q3-9

Asymptotic Analysis

eg3 $\underbrace{Q(w_T)} = \underbrace{\left\langle \frac{w_T}{\|w_T\|^2}, u_1 \right\rangle^2}_{\text{Quality of estimate } w_T} \in [0, 1]$

$$Q(z_T) = 1 - \frac{\sum_{i=2}^n \lambda_i^{2*} z_0^2(i)}{\underbrace{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)}_{\text{approximation error}}}$$

$$Q(z_T) = \frac{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)} - \frac{\sum_{i=2}^n \lambda_i^{2*} z_0^2(i)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)}$$

$$Q(z_*) = \frac{\lambda_1^{2*} z_0^2(1)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)} \quad \text{!s what I want to show.}$$

p-norm

$$Q(w_*) = \left\langle \underbrace{\frac{w_*}{\|w_*\|_2}, u_1} \right\rangle^2 \quad \left(|x_1|^p + |x_2|^p + \dots + |x_n|^p \right)^{\frac{1}{p}}$$

$$= \frac{\langle w_* \cdot u_1 \rangle^2}{\|w_*\|_2^2} = \frac{\langle \sum w_{*-1} u_1 \rangle^2}{\|w_*\|_2^2}$$

$$\sum u_i = \lambda_i u_i$$

from Def of Eigenvalue.

$$= \frac{\langle \boxed{} \boxed{} \boxed{} \rangle^2}{\|w_*\|_2^2}$$

$$z_*(i) = \lambda_i^{2*} \underbrace{z_0(i)}_{\downarrow}$$

$$= \frac{\langle \sum u_i, w_0 \rangle^2}{\dots}$$

$$z_0(i) = \langle u_i, w_0 \rangle$$

$$= \frac{\langle \lambda_i^{2*} u_i, w_0 \rangle^2}{\|w_*\|_2^2}$$

$$\frac{\lambda_i^{2*} z_0^2(i)}{\|w_*\|_2^2}$$

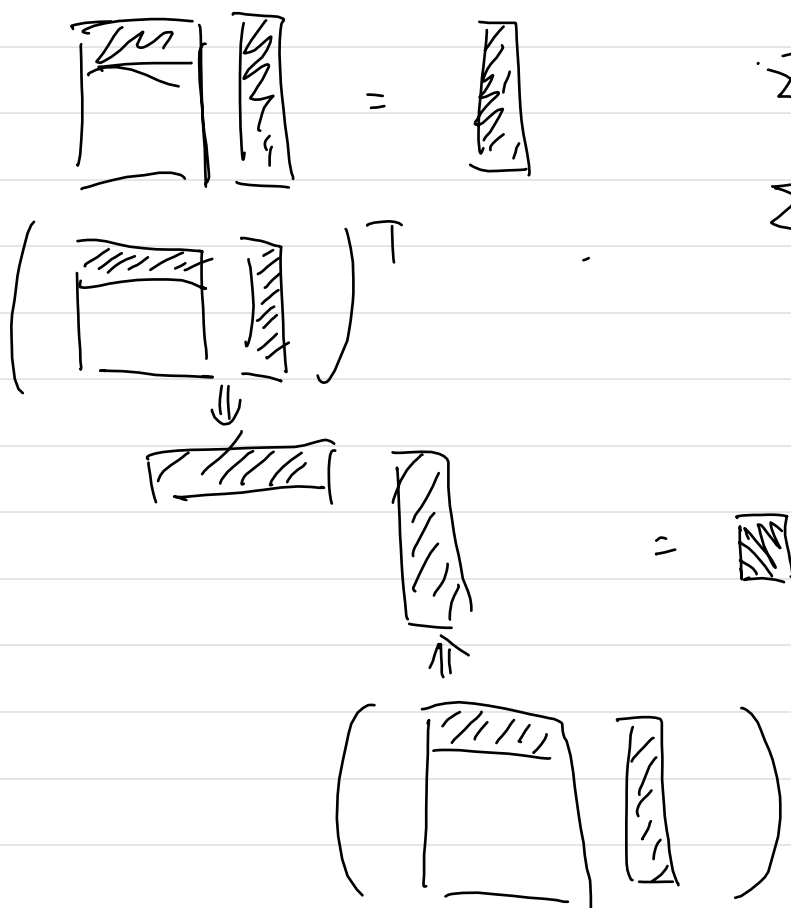
$$Q(w_t) = \frac{\lambda_i^{2*} z_0^2(i)}{|w_t|_2^2}$$

$$\Sigma v_i = \lambda_i v_i$$

$$w_t = \Sigma w_{t-1} = \Sigma^t w_0$$

$$|w_t|_2^2 = \langle \Sigma^t w_0, \Sigma^t w_0 \rangle$$

$$\text{num}(\lambda_i^{2*} z_0^2(i))$$



$$z_0(i) = v_i w_0$$

$$\Sigma v_i = \lambda_i v_i$$

from what we want to show

$$\hookrightarrow \underbrace{\|w\|_2^2}_{= \sum_{i=1}^n w_i^2} = \sum_{i=1}^n \lambda_i^2 \underbrace{x_0(i)^2}_{\langle v_i, w_0 \rangle}$$

$$\sum_{i=1}^n (\lambda_i^2 \langle v_i, w_0 \rangle^2) \xrightarrow{\quad}$$

$$w = \begin{bmatrix} w_1 \\ \vdots \\ w_n \end{bmatrix} = \begin{bmatrix} \Sigma \end{bmatrix}^T \begin{bmatrix} w_0 \end{bmatrix}$$

$$\Sigma v_i = \lambda_i v_i$$

$$\Sigma^T v_i = \lambda_i^T v_i$$

Ah!

$$\|v_i\|_2^2 = 1$$

let's use above one.

$$\sum v_i = \lambda_i$$

$$|w_1|_2^2 = |w_1|_2^2 \underbrace{|u_i|_2^2}$$

Cauchy-Schwarz
inequality

eigenvector is unit-length vector

should be $\geq$ $\Rightarrow$

$$= |\sum^* w_0|_2^2 |u_i|_2^2$$

$$\Rightarrow |\sum^* u_i w_0|^2$$

$$= \left| \sum_{i=1}^n \lambda_i^* u_i w_0 \right|^2$$

$$= \sum_{i=1}^n \lambda_i^{2*} \lambda_0^2(i)$$

$$\sum^* u_i = \lambda_i^* u_i$$

... $\otimes$

$$\text{So, } Q(w_1) = \left\langle \frac{w_1^*}{|w_1|_2}, u_1 \right\rangle^2$$

$$= \frac{1}{|w_1|_2} \gamma \langle w_1^*, u_1 \rangle^2$$

$$= \frac{1}{|w_1|_2} \langle \sum^* w_0, u_1 \rangle^2$$

$$= \frac{1}{|w_1|_2} \langle \sum_i^* u_i, w_0 \rangle^2$$

$$\sum u_i = \lambda_i u_i$$

$$= \frac{1}{|w_1|_2} \lambda_i^{2*} \langle u_i, w_0 \rangle^2 = \frac{1}{|w_1|_2} \lambda_i^{2*} \lambda_0^2(i)$$

$$Q(w^*) = \frac{1}{\|w^*\|_2} \left(\lambda_1^{2*} z_0^2(1) \right)$$

since $\star$

$$= \frac{\lambda_1^{2*} z_0^2(1)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)}$$

$$= \frac{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i) - \sum_{i=2}^n \lambda_i^{2*} z_0^2(i)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)}$$

$$= 1 - \frac{\sum_{i=2}^n \lambda_i^{2*} z_0^2(i)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)}$$

Q.E.D.

Then, evaluate approximation error

$$\begin{aligned} \frac{\sum_{i=2}^n \lambda_i^{2*} z_0^2(i)}{\sum_{i=1}^n \lambda_i^{2*} z_0^2(i)} &= \frac{\sum_{i=2}^n \lambda_i^{2*} z_0^2(i)}{\lambda_1^{2*} z_0^2(1) + \sum_{i=2}^n \lambda_i^{2*} z_0^2(i)} \\ &= \frac{\sum_{i=2}^n \left(\frac{\lambda_i}{\lambda_1}\right)^{2*} z_0^2(i)}{z_0^2(1) + \sum_{i=2}^n \left(\frac{\lambda_i}{\lambda_1}\right)^{2*} z_0^2(i)} \\ &\leq \frac{1}{z_0^2(1)} \left(\sum_{i=2}^n \left(\frac{\lambda_i}{\lambda_1}\right)^{2*} z_0^2(i) \right) \\ &= O\left(\left(\frac{\lambda_2}{\lambda_1}\right)^{2*}\right) \end{aligned}$$