

17A Q3 - f

$$Z_t(i) = \langle u_i, w_t \rangle$$

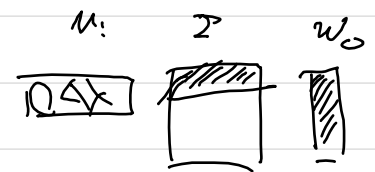
$$= \langle u_i, \sum w_{t-1} \rangle$$

$$= \langle u_i, \sum \sum w_{t-2} \rangle$$

$$= \langle u_i, \sum^T w_0 \rangle$$

$$w_t = \sum w_{t-1} \dots$$

from eq (2)

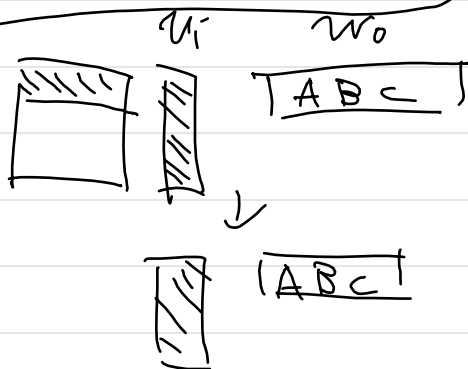
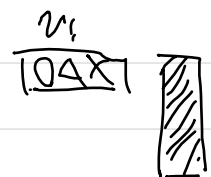


Since I and I^T are symmetric

$\Downarrow$

$$Z_t(i) = \langle \sum^T u_i, w_0 \rangle$$

$\downarrow$



here u_i is eigenvector

$$I u_i = \lambda_i u_i \quad (i = 1, \dots, p)$$

$$\Leftrightarrow \sum^T u_i = \lambda_i^T u_i$$

$$z_i(\star) = \langle \Sigma^T v_i, w_0 \rangle$$

$$= \langle \underbrace{\lambda_i^T}_{\uparrow} v_i, w_0 \rangle$$

scalar

$$= \lambda_i^T \underbrace{\langle v_i, w_0 \rangle}$$

$$= \underbrace{\lambda_i^T z_0(i)}_{\star} \quad \uparrow$$

from definition of $z_0(i)$