

17AQ3 - 7

Let

$$w_0 = \begin{pmatrix} w_1 \\ \vdots \\ w_p \end{pmatrix} \quad v = \begin{pmatrix} v_1 \\ \vdots \\ v_p \end{pmatrix}$$

$$\begin{aligned} \mathbb{E}[\langle w_0, v \rangle^2] &= \mathbb{E}\left[\left(\sum_{i=1}^p x_i v_i \right)^2 \right] \\ &= \mathbb{E}\left[\sum_{i=1}^p \sum_{j=1}^p x_i x_j v_i v_j \right] \\ &= \sum_{i=1}^p \sum_{j=1}^p \mathbb{E}[x_i x_j v_i v_j] \\ &= \sum_{i=1}^p \sum_{j=1}^p v_i v_j \underbrace{\mathbb{E}[x_i x_j]}_{\uparrow} \end{aligned}$$

V is unit-length vector

$$w_0 = \begin{pmatrix} x_1 \\ \vdots \\ x_p \end{pmatrix} \sim N\left(0, \frac{1}{P} I_{P \times P}\right)$$

$$\text{Cov}(x_i, x_j) = \underbrace{\mathbb{E}[x_i x_j]}_{\substack{\text{from} \\ \text{definition}}} - \underbrace{\mathbb{E}[x_i] \mathbb{E}[x_j]}_{\substack{=0 \\ =0}}$$

$$\begin{cases} 0 & \text{if } i \neq j \\ \frac{1}{P} & \text{if } i = j \end{cases}$$

element of
variance-covariance-matrix

covariance
variance (diagonal)

Then,

$$\mathbb{E}[\langle w_0, u \rangle^2] = \sum_{i=1}^P \sum_{j=1}^P u_i u_j \mathbb{E}[x_i x_j]$$

$$= \underbrace{\sum_{i=1}^P \|u\|_i^2}_{\text{unit vector}} \times \underbrace{\sum_{i=1}^P \sum_{j=1}^P \mathbb{E}[x_i x_j]}_{\downarrow}$$

Since unit vector —

$$= 1 \quad \frac{1}{P}$$

$$\approx \frac{1}{P}$$

17A-Q3-f

固有ベクトルの直行性

Let $(U) = [u_1 \dots u_p]$... denote

orthogonal matrix of eigenvectors
of Σ

$$\left(\begin{array}{l} \Sigma = U \Sigma V^T \text{ (Singular Value Decomposition)} \\ A = X \Lambda X^{-1} \text{ (Eigenvalue Decomposition)} \end{array} \right)$$

$$U \Sigma V^{-1} = \begin{pmatrix} \lambda_1 & \dots & \lambda_n \end{pmatrix}$$

scalar dynamics,

$$w_{t+1} = \Sigma w_t \quad z_t(\cdot) = \lambda_i^* \Sigma(\cdot)$$

$$z_0(\cdot) = \langle v_i, w_0 \rangle \quad \text{where}$$

Σ の固有ベクトル v_i を継続するべきだった

行を P とする $P^{-1} \Sigma P$ が Σ である

正角成分(=持つ正角な) が v_i と

縦ベクトル

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \underbrace{\begin{pmatrix} b_1 \\ b_2 \end{pmatrix}}_{\text{縦ベクトル}} = \begin{pmatrix} a_{11}b_1 + a_{12}b_2 \\ a_{21}b_1 + a_{22}b_2 \end{pmatrix}$$

縦ベクトル (column vector)

横ベクトル

$$(a_1 \ a_2) \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} = (a_1 b_{11} + a_2 b_{21}, a_1 b_{12} + a_2 b_{22})$$

$$U = [u_1, \dots, u_n]$$

$$U^{-1} \Sigma U = \Delta \Leftrightarrow \Sigma U = \Delta U$$

$$\sum u_i = \lambda i u_i$$

$$\sum \begin{array}{|c|c|c|} \hline & & \\ \hline & & \\ \hline \end{array} u_i = \begin{array}{|c|c|c|} \hline \lambda_1 & 0 & \\ \hline 0 & \ddots & \lambda_n \\ \hline \end{array} \begin{array}{|c|c|c|} \hline & & \\ \hline & & \\ \hline \end{array} u_i$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} ax+by \\ cx+dy \end{pmatrix}$$

(1)
(2)

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} ax+by \\ cx+dy \\ cz+dw \end{pmatrix}$$

$$\sum U = \Lambda V$$

$$\begin{array}{c} \boxed{\text{#}} \quad \boxed{\text{|||}} \\ \hline \end{array} = \begin{array}{c} \boxed{P_{00}} \quad \boxed{\text{|||}} \\ \hline \end{array}$$

正規ベクトル

二つに分ける

$$V = [u_1, \dots, u_n]$$

$$u_i = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

(=非直交)

正交・直交

$$P u_i = \Lambda u_i$$

$$\begin{array}{c} \boxed{\text{#}} \quad \boxed{\text{|||}} \\ \hline \end{array} = \begin{array}{c} \boxed{P_{00}} \quad \boxed{\text{|||}} \\ \hline \end{array} \rightarrow \begin{array}{c} \boxed{\text{|||}} \\ \hline \end{array}$$

ノルムを取る

i -th eigenvector

$$\langle u_i, w_0 \rangle = z_0(i)$$

$$x^{(0)} = c_1 \frac{u_1}{\sqrt{2}} + \dots + c_n \frac{u_n}{\sqrt{2}}$$

標準形独立な固有ベクトル

$$= U_C$$

$$x^{(0)} = \sum_{k=1}^K a_k \text{bit}_k u_k$$

$$x^{(1)} = x^{(0)} = \sum U_C = \underbrace{U U^\top}_{\Sigma} \sum U_C$$

$$= U (\lambda_1 \dots \lambda_K) C$$

$$= a_1 c_1 u_1 + \dots + a_n c_n u_n$$

今回 $\sum a_k \text{bit}_k u_k < \sqrt{K}$

$$x^{(1)} = \underbrace{\sum \dots \sum}_{K \text{個}}, U_C = a_1 c_1 u_1 + \dots + a_n c_n u_n$$

$$= a_1 c_1 \underbrace{\sum u_1 + \dots + \left(\frac{a_n}{a_1}\right) \left(\frac{c_n}{c_1}\right) u_n}_{0}$$

$$\lim_{T \rightarrow \infty} x^{(T)} = a_1 c_1 u_1 = u_1$$

↑ 定収束已固有ベクトル

$U = \{u_1, \dots, u_n\}$ は元ベクトルを Σ の固有ベクトル

$$U \Sigma U^{-1} = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} \Leftrightarrow U \Sigma = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} U$$

$$\begin{array}{c} \text{mm} \\ \boxed{\quad} \end{array} \begin{array}{c} \Sigma \\ \boxed{\quad} \end{array} = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} \begin{array}{c} \text{mm} \\ \boxed{\quad} \\ \downarrow \\ u_1 \end{array}$$

$$\boxed{\quad} = \begin{array}{c} \text{mm} \\ \boxed{\quad} \end{array} \begin{array}{c} \Sigma \\ \boxed{\quad} \end{array} = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} \boxed{\quad}$$

$$z_0(\cdot) = \langle u_0, w_0 \rangle$$

行列式が変換可能とすると
零形独立なベクトルを用いてもよびます

$$x_0 = c_1 u_1 + \dots + c_n u_n$$

$$= \sum c_i$$

は上に書いたとおり

$$x_1 = \sum x_0 = \sum c_i u_i = \underline{U} \underline{V} \Sigma \underline{U}$$

\Leftarrow

$$= U \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} U^{-1}$$

$$x_{t+1} = \sum x_t$$

$$= \lambda_1 c_1 u_1 + \dots + \lambda_n c_n u_n$$

$$= \lambda_1 c_1 u_1 + \dots + \lambda_n c_n u_n$$

とおなじ

∴ x^* は A の固有ベクトル

$$\begin{aligned} w_{t+1} &= \sum w_t \\ &= \lambda_1^{(t+1)} c_1 u_1 + \left(\frac{\lambda_2}{\lambda_1}\right)^{(t+1)} \frac{c_2}{c_1} u_2 + \dots + \left(\frac{\lambda_n}{\lambda_1}\right)^{(t+1)} \frac{c_n}{c_1} u_n \end{aligned}$$

$n \rightarrow \infty$

$$w_{t+1} = \lambda_1^{(t+1)} c_1 u_1 \rightarrow$$

定数倍の固有ベクトル

$$\begin{aligned} \text{e.g. } x_2 &= \sum x_1 \\ &= UU^{-1} \sum x_1 \\ &= UU^{-1} \sum U (\lambda_1 \dots \lambda_n) c_1 \end{aligned}$$